

Robust Design Optimization with OptiY®

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OptiY e.K. Germany

Probabilistik – Workshop

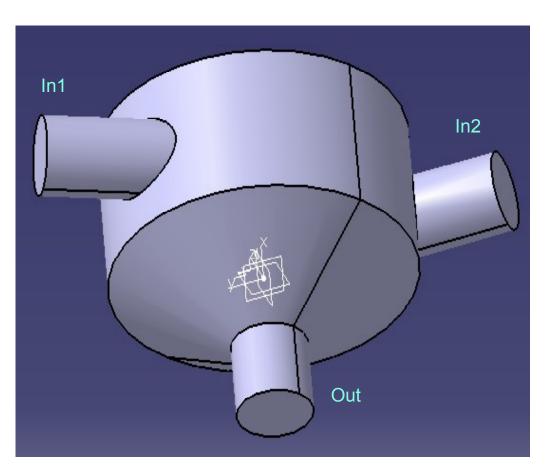
7-8 Oktober 2010 in Dresden

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Design of Static Mixer with Uncertainties



- Inlet in1 and in2, Outlet out
- Inlet temperature in1Temp, in2Temp
- Inlet velocity: in2Vel, in2Vel
- Design goal: outlet temperature
- 4 variable and uncertainty design parameters: in1radius, in2angle, in1Vel and in2Vel
- 4 fix and uncertainty process and environment parameters: Capacity, Conductivity, in1Temp and in2Temp

| Name | Nominal | Tolerance | Unit | Comment |
|--------------|---------|-----------|--------------|------------------------|
| in1radius | 0.6 | 0.6 | mm | in1 radius |
| in2angle | 40 | 60 | deg | in2 angle |
| in1Vel | 3 | 3 | m s^-1 | in1 velocity |
| in2Vel | 3 | 3 | m s^-1 | in2 velocity |
| Capacity | 4181.7 | 41.817 | J kg^-1 K^-1 | specific heat capacity |
| Conductivity | 0.6069 | 0.006069 | W m^-1 K^-1 | thermal conductivity |
| in1Temp | 315 | 3.15 | к | in1 temperature |
| in2Temp | 285 | 2.85 | к | in2 temperature |

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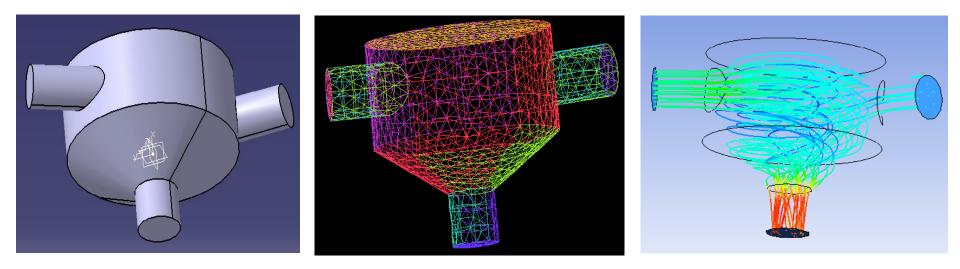


CAD/CAE -Systems

Geometry: CATIA

Meshing: ICEM

Fluid Dynamic: CFX



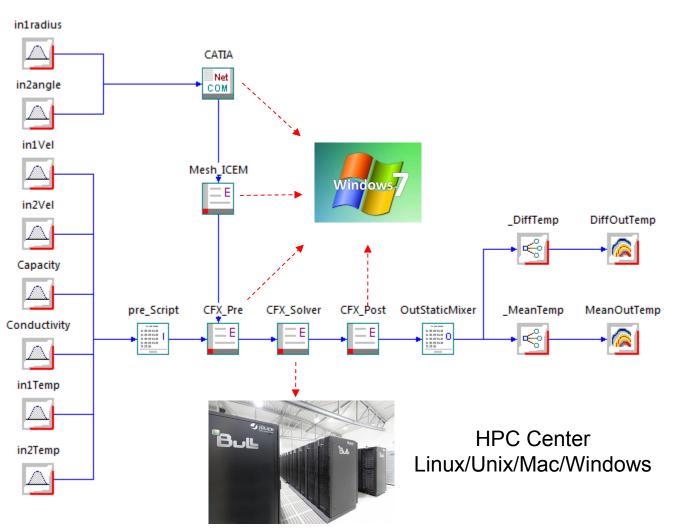
Specialized Systems:

- Fast and user-friendly handling of the software
- · Competence and Know-How through long time research and development
- Detailed system component behaviour
- · Import and export in standard format for data exchange
- Team working: designer and CAE-specialist

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Process Workflow



Use-friendly graphical process workflow with distributed computing:

• Fast process (CAD, Meshing, Pre- and Post-Processing) in comfortable OS Windows with MS Office

• Computationally intensive process (Solver) in HPC-Center via SSH Networking and FTP File Transfer



DoE: Adaptive Gaussian Process

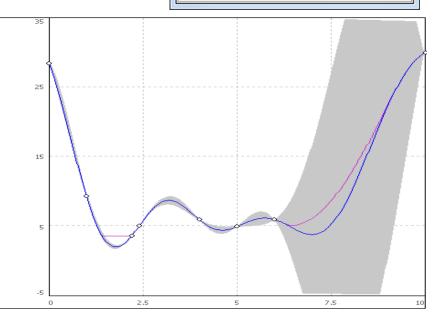
Providing information about expected improvement and uncertainty of the total design space. Extremely efficient design of experiment. The required number of model calculations (points) depends on:

- Number of design parameters
- Degree of response nonlinearity
- Correlation between design parameters

For Static Mixer:

- 8 design parameters
- 1 design goal: out mean temperature
- Initial sampling: 40 points (Sobol Sampling)
- Covariance function = Square Exponential
- Polynomial order = 0
- High accuracy of the response surface
- Total sampling: 88 points after 8 loops

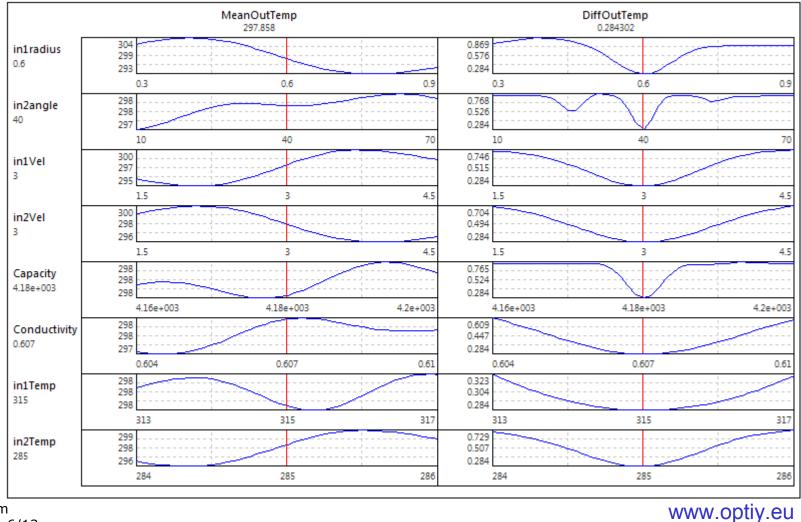
| Property 🛛 | | | | |
|----------------------|------------------|------------------|--|--|
| Design of Experiment | | | | |
| Me | ethod | Sampling Methods | | |
| Pa | rameter | Sobol | | |
| Sa | mple Size | 40 | | |
| Ad | aptive Design | True | | |
| Ac | curacy [110] | 5 | | |
| Su | ggested Points | 6 | | |
| Ma | aximal Points | 100 | | |
| Vir | tual Sample Size | 100000 | | |
| Dis | tribution Points | 50 | | |
| Ra | ndom Generator | Init | | |



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Design Space Visualization: 2D Section Diagrams



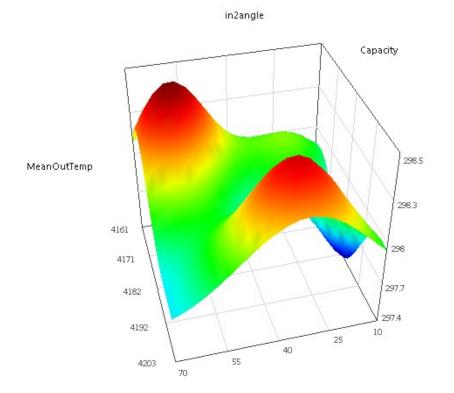
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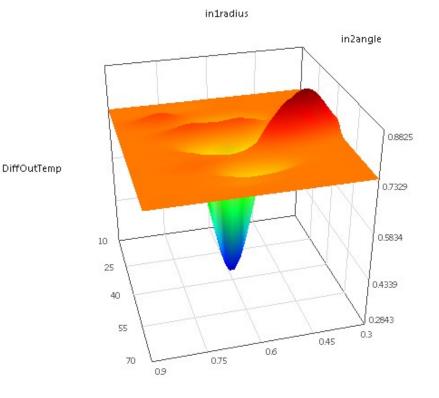


Design Space Visualization: 3D Graphics

Out Mean Temperature

Out Temperature Difference



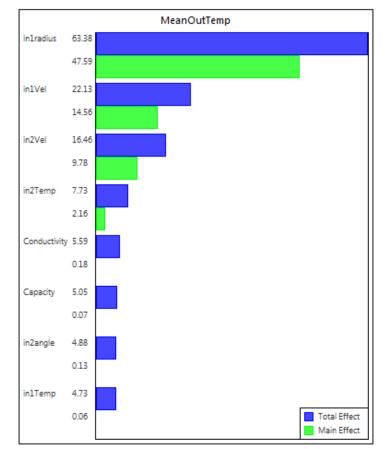


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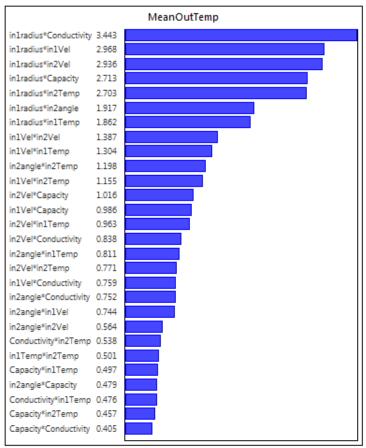
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Global Nonlinear and Quantitative Sensitivity Analysis



Design Parameter Importance



Design Parameter Interactions

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Design Optimization and Probabilistic Simulation

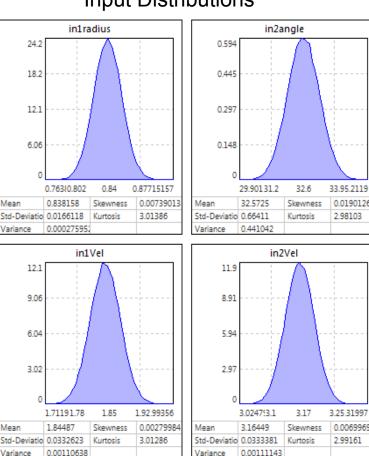
Design Optimization

Design goal: minimize the out temperature to get the optimal design point in the design space (Table: optimal design parameters with manufacturing tolerances)

| 🗠 Design Parameters | | | | |
|---------------------|------------|----------|--------------|------------------------|
| Name | Nominal | Toleran | Unit | Comment |
| in1radius | 0.8381008 | 0.1 | mm | in1 radius |
| in2angle | 32.5715075 | 4 | deg | in2 angle |
| in1Vel | 1.84504689 | 0.2 | m s^-1 | in1 velocity |
| in2Vel | 3.16437001 | 0.2 | m s^-1 | in2 velocity |
| Capacity | 4181.7 | 41.817 | J kg^-1 K^-1 | specific heat capacity |
| Conductivity | 0.6069 | 0.006069 | W m^-1 K^-1 | thermal conductivity |
| in1Temp | 315 | 3.15 | К | in1 temperature |
| in2Temp | 285 | 2.85 | К | in2 temperature |
| | | | | |

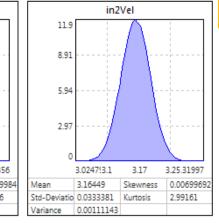
Design Robustness

Tolerances of design parameters cause variability of the out temperature: quality and reliability in batch production

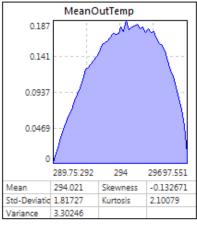


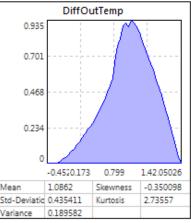
Input Distributions

0.187 0.141 0.0937 0.0469 0.0190126 294.021 Mean Std-Deviatio 1.81727 Variance 3.30246



Output Distributions





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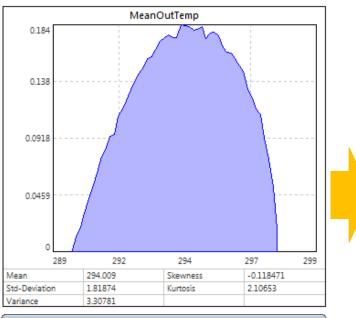
Virtual Sampling Size: 100.000 Points



Fast Robust Design Optimization

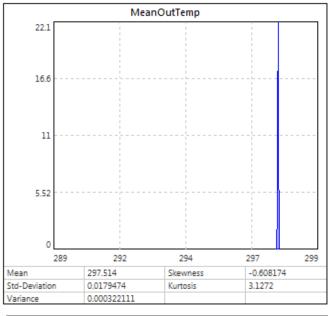
Taguchi Quality Loss Function: L = Cost*(Variance + (Mean – Target)²)

Nominal Design



| 🗠 Design Parameters 💿 🗉 🔀 | | | | |
|---------------------------|------------|----------|--------------|------------------------|
| Name | Nominal | Toleran | Unit | Comment |
| in1radius | 0.8381008 | 0.1 | mm | in1 radius |
| in2angle | 32.5715075 | 4 | deg | in2 angle |
| in1Vel | 1.84504689 | 0.2 | m s^-1 | in1 velocity |
| in2Vel | 3.16437001 | 0.2 | m s^-1 | in2 velocity |
| Capacity | 4181.7 | 41.817 | J kg^-1 K^-1 | specific heat capacity |
| Conductivity | 0.6069 | 0.006069 | W m^-1 K^-1 | thermal conductivity |
| in1Temp | 315 | 3.15 | К | in1 temperature |
| in2Temp | 285 | 2.85 | К | in2 temperature |
| 1 | | | | |

Robust Design



| 🗠 Design Parameters 🛛 🗖 🕮 🔀 | | | | |
|-----------------------------|-------------|----------|--------------|------------------------|
| Name | Nominal | Toleran | Unit | Comment |
| in1radius | 0.304053239 | 0.1 | mm | in1 radius |
| in2angle | 50.165564 | 4 | deg | in2 angle |
| in1Vel | 1.51153931 | 0.2 | m s^-1 | in1 velocity |
| in2Vel | 4.41115449 | 0.2 | m s^-1 | in2 velocity |
| Capacity | 4181.7 | 41.817 | J kg^-1 K^-1 | specific heat capacity |
| Conductivity | 0.6069 | 0.006069 | W m^-1 K^-1 | thermal conductivity |
| in1Temp | 315 | 3.15 | К | in1 temperature |
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Minimizing the variance of the out temperature:

The mean temperature and its variance conflict each other. The extreme cases are nominal design and robust design:

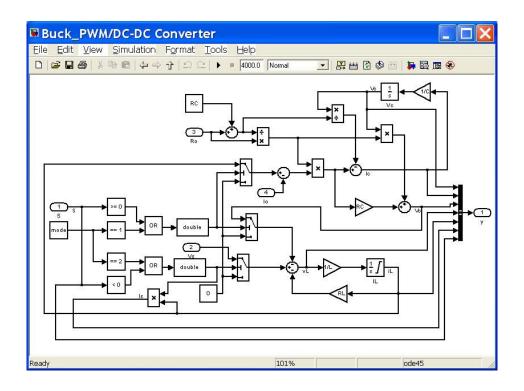
- Low mean temperature versus high variance
- High mean temperature versus low variance

Multi-Objective Design Optimization



Code-Export of Surrogate Model for System Simulation

- Automatic Code-Export in C, Modelica or Matlab
- Fast surrogate model for total system simulation (e.g. Matlab/Simulink, MBS-Simulator)
- Development of controller or mechanical system in case of co-simulation with fluid dynamics



```
double F(double i, double s)
 double p[2];
 double x1[2];
 double x2[2];
 double y = -45.7372055;
 y = y+10.5254853 \pm pow(i,1);
 y = y+4.52081477 \pm pow(s,1);
p[0] = 0.151298213;
p[1] = 0.928373134;
x1[0] = i;
x1[1] = s;
x2[0] = 5.01;
x2[1] = 2.02;
 y = y-183.985579*Covariance(x1,x2,p);
x2[0] = 0.01;
x2[1] = 0.02;
y = y - 8524.5598 * Covariance(x1,x2,p);
x2[0] = 2.01;
x2[1] = 0.02;
 y = y+27577.7253*Covariance(x1,x2,p);
x2[0] = 10.01;
x2[1] = 4.02;
y = y-1042.30105*Covariance(x1,x2,p);
 return y;
```



Conclusion

- Design of technical system with uncertainties requires efficient computing of product model. Adaptive Gaussian process is the best approach for robust design optimization.
- The meta-model of the static mixer with 8 design parameters needs totally only 88 model calculations and turn out the response surface of the outlet temperature accurately.
- Based on the meta-model, the robust design process of the static mixer has been demonstrated. It leads into a multi-objective design optimization task
- **OptiY**® is a user-friendly multidisciplinary software platform also for robust design of large technical systems with uncertainties